

Vemo:

Simetrične matrice imajo vse lastne vrednosti realne.

A simetrična, $\lambda_1, \dots, \lambda_n \in \mathbb{R}$ l.v.

$$A = Q D Q^T \quad D = \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{bmatrix}, \quad Q = [Q^{(1)} \dots Q^{(n)}]$$

$$A Q^{(i)} = \lambda Q^{(i)}$$

$$\vec{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} \quad A \vec{x} = \begin{bmatrix} a_{11} & \dots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{n1} & \dots & a_{nn} \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n \\ \vdots \\ a_{n1}x_1 + a_{n2}x_2 + \dots + a_{nn}x_n \end{bmatrix}$$

$$\vec{x}^T A \vec{x} = [x_1 \dots x_n] [A] \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} = x_1(a_{11}x_1 + \dots + a_{1n}x_n) + \dots + x_n(a_{n1}x_1 + \dots + a_{nn}x_n) =$$

$$= a_{11}x_1^2 + \dots + a_{nn}x_n^2 +$$

$$(a_{12} + a_{21})x_1x_2 + (\quad)x_1x_3 + \dots + (\quad)x_{n-1}x_n$$

kwadratna forma

Def: Za $A \in \mathbb{R}^{n \times n}$ imenujemo $\vec{x}^T A \vec{x}$ kwadratna forma matrice A.

Primer: $A = \begin{bmatrix} 5 & 2 \\ 0 & 5 \end{bmatrix}$ $\vec{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$ $\vec{x}^T A \vec{x} = 5x_1^2 + 5x_2^2 + 2x_1x_2 + 0x_2x_1$

enako: $B = \begin{bmatrix} 5 & 0 \\ 2 & 5 \end{bmatrix}$ in $C = \begin{bmatrix} 5 & 1 \\ 1 & 5 \end{bmatrix}$

za vsako kv. formo obstaja natanko 1 simetrična matrica, ki ji ustreza.

Def: Naj bo $A \in \mathbb{R}^{n \times n}$ simetrična. Pravimo, da je A ...

① **Positivno semidefinitna**, če je njena kvadratna forma nenegativna za vsake \vec{x} . $\forall \vec{x} \in \mathbb{R}^n. \vec{x}^T A \vec{x} \geq 0$.

② **Positivno definitna**, če $\forall \vec{x} \in \mathbb{R}^n. \vec{x} \neq \vec{0}. \vec{x}^T A \vec{x} > 0$.

③ **Negativno semidefinitna**, če $\forall \vec{x} \in \mathbb{R}^n. \vec{x}^T A \vec{x} \leq 0$

④ **Negativno definitna**, če $\forall \vec{x} \in \mathbb{R}^n. \vec{x} \neq \vec{0}. \vec{x}^T A \vec{x} < 0$.

⑤ **Nedefinitna**, če nič od naštetega

(tj. $\exists \vec{x} \in \mathbb{R}^n: \vec{x}^T A \vec{x} > 0$ in $\exists \vec{y} \in \mathbb{R}^n: \vec{y}^T A \vec{y} < 0$)

linearna menjava spremenljivk

Kv.f. diag matr. so zelo lepe! $\vec{u} = Q^T \vec{x}$

$$A = Q D Q^T \rightsquigarrow \vec{x}^T A \vec{x} = \vec{x}^T Q D Q^T \vec{x} = \vec{u}^T D \vec{u}$$

kv. forma

plus: v originalnih spremenljivkah

spremenili smo coord. sist.

kv. forme

v novih sprem.

u_1, \dots, u_n

plus: imamo mešanil členov

diagonalizirali smo kv. formo

Primer: $A = \begin{bmatrix} 5 & 1 \\ 1 & 5 \end{bmatrix}$ $\vec{x}^T A \vec{x} = 5x_1^2 + 5x_2^2 + 2x_1x_2$

Kaj predstavlja $5x_1^2 + 5x_2^2 + 2x_1x_2 = 24$?

Diagonalizirajmo A !

$\lambda_1 = 4, \lambda_2 = 6 \rightarrow \vec{v}_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \vec{v}_2 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$ $\vec{x}^T A \vec{x} = \vec{u}^T D \vec{u} = 4u_1^2 + 6u_2^2$

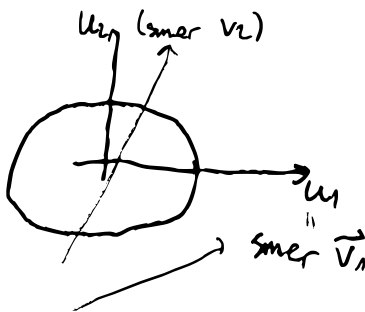
$D = \begin{bmatrix} 4 & 0 \\ 0 & 6 \end{bmatrix}, Q = \frac{1}{\sqrt{2}} \begin{bmatrix} -1 & 1 \\ 1 & 1 \end{bmatrix}$ $\vec{u} = Q^T \vec{x}$

$\begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = \frac{1}{\sqrt{2}} \begin{bmatrix} -1 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$ $u_1 = \frac{1}{\sqrt{2}} (-x_1 + x_2)$
 $u_2 = \frac{1}{\sqrt{2}} (x_1 + x_2)$

Torej, prejšnja enačba se prepíše v

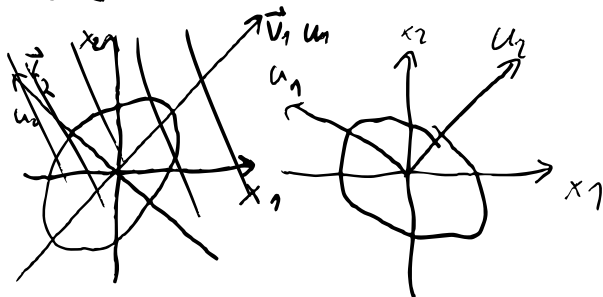
$$4u_1^2 + 6u_2^2 = 24 \quad | :24 \quad (\text{ampak vnovih spremenjih, kat!})$$

$$\frac{u_1^2}{(\sqrt{6})^2} + \frac{u_2^2}{2^2} = 1$$



$$\vec{x} = Q\vec{u}$$

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = [Q^{(1)} \quad Q^{(2)}] \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$$



izrek:

$A \in \mathbb{R}^{n \times n}$ simetrična

① A je PSD natanko tedaj ko so vse lastne vrednosti matrice A nenegativne.

(dokaz: A PSD $\Rightarrow \vec{x}^T A \vec{x} \geq 0$ za vse $\vec{x} \in \mathbb{R}^n$)

$$\Rightarrow \vec{u}^T D \vec{u} \geq 0 \quad \text{za vse } \vec{u} \in \mathbb{R}^n$$

$$\Rightarrow \lambda_1 u_1^2 + \lambda_2 u_2^2 + \dots + \lambda_n u_n^2 \geq 0 \quad \text{za vse } \vec{u} \in \mathbb{R}^n$$

$$\hookrightarrow u_j = 1 \quad u_0 = u_1 = \dots = u_{j-1} = u_{j+1} = \dots = u_n = 0$$

$$\Rightarrow \lambda_j \geq 0$$

$$\text{Če } \lambda_1, \dots, \lambda_n \geq 0 \Rightarrow \vec{x}^T A \vec{x} = \lambda_1 \hat{u}_1^2 + \dots + \lambda_n \hat{u}_n^2 \geq 0 \Rightarrow A \text{ PSD } \square$$

① A je PD $\Leftrightarrow \lambda_1, \dots, \lambda_n > 0$.

② A je NSD $\Leftrightarrow \lambda_1, \dots, \lambda_n \leq 0$

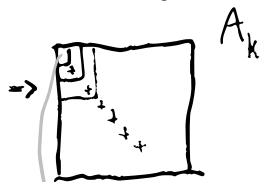
③ A je ND $\Leftrightarrow \lambda_1, \dots, \lambda_n < 0$

④ A je indefinitna $\Leftrightarrow \lambda_1 > 0, \lambda_2 < 0$

$$\begin{bmatrix} \vec{x}^T \\ 0 \dots 0 \end{bmatrix} \begin{bmatrix} A \\ \vdots \\ \vdots \end{bmatrix} \begin{bmatrix} \vec{x} \\ \vdots \\ \vdots \end{bmatrix} > 0 \quad \text{za } \forall \vec{x} \in \mathbb{R}^n$$

se ne upošteva zaradi ničel

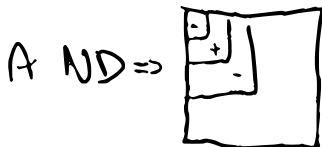
A PD \Rightarrow "levi zgornji vogal" matrike A PD



vsaka 1×1 matrika ima 1 pozitivno lvr.

izrek (Sylvester)

A PD $\Rightarrow \det(A_k) > 0$ za $k=1, 2, \dots, n$
velja tudi \Leftarrow



A ND $\Rightarrow \det(A_k) > 0$ za sode $k, 1 \leq k \leq n$
 $\det(A_k) < 0$ za lihe $k, 1 \leq k \leq n$

$$A = BB^T \text{?}$$

① BB^T je vedno:

- simetrična
- PSD

② Naj bo $A \in \mathbb{R}^{n \times n}$

$$A = QDQ^T =$$

$$= QEQE^T =$$

$$= (QE)(QE)^T$$

$$B := QE$$

$$A = BB^T$$

PD.

$$D = \begin{bmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{bmatrix} > 0$$

$$E = \begin{bmatrix} \sqrt{\lambda_1} & & 0 \\ & \ddots & \\ 0 & & \sqrt{\lambda_n} \end{bmatrix} \quad E^2 = D$$

$$E = E^T!$$

izrek:

A obrnjiva $n \times n$ matrika

$A = BB^T$ za neko $B \in \mathbb{R}^{n \times n}$, $\text{rang } B = n$, natanko tedaj,

ko je A PD. (in seveda simetrična)

V posebnem:

Naredimo QR faktorizacijo matrike B^T .

$$B^T = QR \quad Q \text{ ortogonalna, } B \text{ zg.} \quad L = R^T \text{ sp.}\Delta$$

$$A \text{ je PD} \Leftrightarrow A = BB^T = R^T \underbrace{Q^T Q}_I R = R^T R = \underbrace{L}_{\Delta} \underbrace{L^T}_{\Delta}$$

Razcep Choleskega

Izrek: (razcep Choleskega)

A obrnljiva matrika

A ima razcep Choleskega ($A=LL^T$ za obrnljivo sp. Δ .matr.)
natanko tedaj, ko je A PD. (in simetrična)