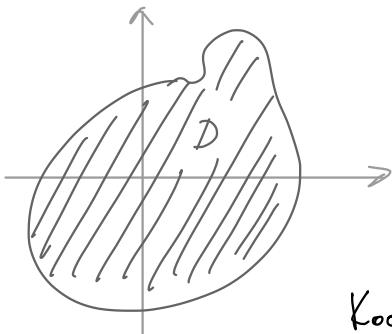


Matematika 1, vaje, 22. 12. 2020

1. Poišči koordinate masnega središča četrтtine kroga; $x^2 + y^2 \leq R^2$, $x \geq 0$, $y \geq 0$, če je gostota v vsaki točki enaka oddaljenosti od izhodišča, tj. $\rho(x, y) = \sqrt{x^2 + y^2}$.

Namig: masa lika $D \subseteq \mathbb{R}^2$ je dana z $m = \iint_D \rho(x, y) dx dy$, koordinati masnega središča pa sta $x^* = \frac{1}{m} \iint_D x \rho(x, y) dx dy$ in $y^* = \frac{1}{m} \iint_D y \rho(x, y) dx dy$. Uvedi polarne koordinate.



$$m = \iint_D \rho(x, y) dx dy$$

to je masa območja D s površinsko gostoto $\rho(x, y)$

Koordinati masnega središča sta:

$$x^* = \frac{1}{m} \iint_D x \rho(x, y) dx dy, \quad y^* = \frac{1}{m} \iint_D y \rho(x, y) dx dy.$$

Postavimo (naivno) v kartezijnih koordinatah:

$$m = \int_0^R \left(\int_0^{\sqrt{R^2 - y^2}} \sqrt{x^2 + y^2} dx \right) dy \dots$$

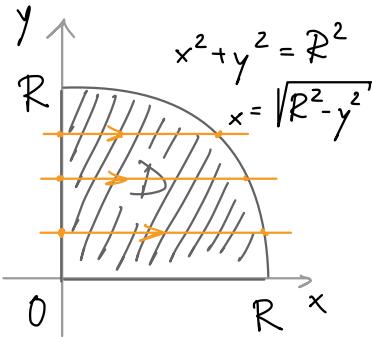
Kaj pa, če uvedemo polarne koordinate?

$$\begin{aligned} x &= r \cos \varphi & \det(J\vec{F}) &= r \\ y &= r \sin \varphi \end{aligned}$$

$$\begin{aligned} m &= \iint_D \rho(x, y) dx dy = \int_0^{\pi/2} \left(\int_0^R \underbrace{\sqrt{r^2 \cos^2 \varphi + r^2 \sin^2 \varphi}}_{r^2} \cdot r dr \right) d\varphi = \\ &= \int_0^{\pi/2} \left(\int_0^R r^2 dr \right) d\varphi = \underbrace{\int_0^{\pi/2} \left(\frac{r^3}{3} \Big|_{r=0}^{r=R} \right)}_{\frac{R^3}{3}} d\varphi = \frac{R^3}{3} \cdot \frac{\pi}{2} = \frac{\pi R^3}{6}. \end{aligned}$$

$$x^* = \frac{1}{m} \iint_D x \rho(x, y) dx dy = \frac{6}{\pi R^3} \int_0^{\pi/2} \left(\int_0^R r \cos \varphi \cdot r^2 dr \right) d\varphi =$$

$$\begin{aligned} &= \frac{6}{\pi R^3} \int_0^{\pi/2} \cos \varphi \underbrace{\left(\frac{r^4}{4} \right)}_{\frac{R^4}{4}} \Big|_{r=0}^{r=R} d\varphi = \frac{6}{\pi R^3} \cdot \frac{R^4}{4} \cdot \underbrace{\sin \varphi \Big|_{\varphi=0}^{\varphi=\frac{\pi}{2}}}_{1} = \frac{3R}{2\pi} \end{aligned}$$



$$y^* = \frac{6}{\pi R^3} \int_0^{\pi/2} \left(\int_0^R r \sin \varphi \cdot r^2 dr \right) d\varphi = \frac{6}{\pi R^3} \left(\int_0^R r^3 dr \right) \left(\int_0^{\pi/2} \sin \varphi d\varphi \right) = \frac{3R}{2\pi}$$

$$\int_{\varphi_1}^{\varphi_2} \left(\int_{R_1}^{R_2} f(r) \cdot g(\varphi) dr \right) d\varphi = \left(\int_{R_1}^{R_2} f(r) dr \right) \cdot \left(\int_{\varphi_1}^{\varphi_2} g(\varphi) d\varphi \right)$$

Koordinate masnega središča sta $(x^*, y^*) = \left(\frac{3R}{2\pi}, \frac{3R}{2\pi} \right)$.

2. Določi maso in koordinate masnega središča homogenega telesa (tj. $\rho(x, y, z) = 1$), ki je omejeno s ploskvama $z^2 = x^2 + y^2$ ter $x^2 + y^2 + z^2 = 4$ in leži v polprostoru $z \geq 0$.

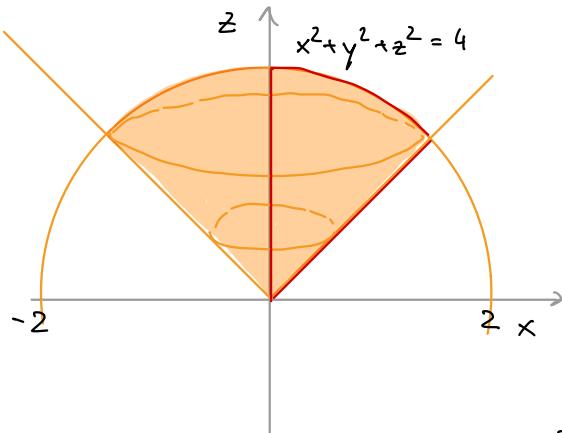
Namig: Vpelji ti sferne oz. krogelne koordinate:

$$x = r \cos \theta \cos \varphi,$$

$$y = r \cos \theta \sin \varphi,$$

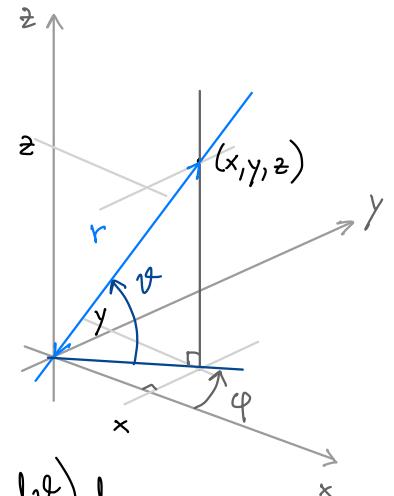
$$z = r \sin \theta,$$

tj. 'novo spremenljivko' $\mathbf{F}(r, \varphi, \theta) = [x, y, z]^\top$ (za katero je $\det(J\mathbf{F}) = r^2 \cos \theta$.)



$$\begin{aligned} x &= r \cos \theta \cos \varphi \\ y &= r \cos \theta \sin \varphi \\ z &= r \sin \theta \end{aligned}$$

$$\det J\mathbf{F} = \frac{r^2 \cos \theta}{2\pi}$$



$$\begin{aligned} m &= \iiint_D \rho(x, y, z) dx dy dz = \int_0^{\pi/4} \left(\int_0^{\pi/2} \left(\int_0^2 1 \cdot r^2 \cos \theta dr \right) d\theta \right) d\varphi = \\ &= \underbrace{\left(\int_0^{2\pi} d\varphi \right)}_{2\pi} \underbrace{\left(\int_{\pi/4}^{\pi/2} \cos \theta d\theta \right)}_{\sin \theta \Big|_{\theta=\pi/4}^{\theta=\pi/2}} \underbrace{\left(\int_0^2 r^2 dr \right)}_{\frac{r^3}{3} \Big|_{r=0}^{r=2}} = 2\pi \left(1 - \frac{\sqrt{2}}{2} \right) \cdot \frac{8}{3} = \frac{8\pi}{3} (2 - \sqrt{2}) \end{aligned}$$

$$z^* = \frac{1}{m} \iiint_D z \cdot \rho(x, y, z) dx dy dz = \frac{1}{m} \int_0^{2\pi} \left(\int_{\pi/4}^{\pi/2} \left(\int_0^2 r \sin \theta \cdot 1 \cdot r^2 \cos \theta dr \right) d\theta \right) d\varphi =$$

$$= \frac{1}{m} \left(\int_0^{2\pi} d\varphi \right) \cdot \underbrace{\left(\int_{-\frac{\pi}{4}}^{\frac{\pi}{2}} \sin \vartheta \cos \vartheta d\vartheta \right)}_{t = \sin \vartheta \rightarrow t \parallel dt = \cos \vartheta d\vartheta} \cdot \underbrace{\left(\int_0^2 r^3 dr \right)}_4 = \frac{2\pi}{m} = \frac{\frac{3}{4}}{\frac{1}{z^4}}.$$

$$\int_{\sqrt{2}/2}^1 t dt = \frac{t^2}{2} \Big|_{t=\sqrt{2}/2}^{t=1} = \frac{1}{2} - \frac{1}{4} = \frac{1}{4}$$

$$x^* = \frac{1}{m} \left(\int_0^{2\pi} \cos \varphi d\varphi \right) = \dots = 0 \dots y^* = 0.$$

4. Določi maso in koordinate masnega središča krogle z neenačbo $x^2 + y^2 + z^2 \leq 2z$, če je njena gostota v vsaki točki enaka oddaljenosti od izhodišča.
Namig: Uvedi krogelne koordinate.

$$x^2 + y^2 + z^2 \leq 2z \dots x^2 + y^2 + z^2 - 2z \leq 0 \quad /+1 \quad \text{to je kroga s polmerom 1 in središčem v } (0, 0, 1).$$

$$m = \int_0^{2\pi} \left(\int_0^{\pi/2} \left(\int_0^1 r \cdot r^2 \cos \vartheta dr \right) d\vartheta \right) d\varphi =$$

$$\rho(x, y, z) = \sqrt{x^2 + y^2 + z^2} = r = \int_0^{2\pi} \left(\int_0^{\pi/2} \cos \vartheta \cdot \frac{r^4}{4} \Big|_{r=0}^{r=2 \sin \vartheta} d\vartheta \right) d\varphi =$$

$$= 4 \int_0^{2\pi} \left(\int_0^{\pi/2} \cos \vartheta \cdot \sin^4 \vartheta d\vartheta \right) d\varphi =$$

$$= 4 \cdot 2\pi \int_0^1 t^4 dt = \frac{8}{5}\pi.$$

$z^* = \frac{1}{m} \cdot \dots$ samostojno doma!

6. Poišči in kasificiraj stacionarne točke spodnjih funkcij.

(a) $f(x,y) = x^3 - 4x^2 + 2xy - y^2$

(b) $g(x,y) = xe^x + 2ye^y + 1$

(c) $h(x,y) = (1 + e^y) \cos x - ye^y$

$$(a) f(x,y) = x^3 - 4x^2 + 2xy - y^2$$

$$\frac{\partial f}{\partial x} = 3x^2 - 8x + 2y = 0 \dots 3x^2 - 8x + 2x = 0 \dots 3x(x-2) = 0$$

$$\frac{\partial f}{\partial y} = 2x - 2y = 0 \dots x = y$$

f ima 2 stacionarne točki $T_1(0,0)$, $T_2(2,2)$.

Ali sta ti dve točki tudi lok. ekstrema?

Tip stac. točke določimo z uporabo Hessejeve mat. f :

$$H_f = \begin{bmatrix} f_{xx} & f_{xy} \\ f_{yx} & f_{yy} \end{bmatrix} = \begin{bmatrix} 6x - 8, & 2 \\ 2, & -2 \end{bmatrix}$$

V stac. točkah je:

$$T_1 : H_f(0,0) = \begin{bmatrix} -8 & 2 \\ 2 & -2 \end{bmatrix} \quad \begin{cases} -8 < 0 \\ \det H_f(0,0) = 12 > 0 \end{cases} \quad \begin{cases} \text{je neg. definitoria} \\ \text{definitna} \end{cases}$$

Torej je T_1 lokalni maksimum.

$$T_2 : H_f(2,2) = \begin{bmatrix} 4 & 2 \\ 2 & -2 \end{bmatrix} \quad \begin{cases} 4 > 0 \\ \det(H_f(2,2)) = -12 \end{cases} \quad \begin{cases} \text{ni} \\ \text{definitna} \end{cases}$$

Torej T_2 ni lokalni ekstrem (je sedlasta točka).